

*Finding a hole in the plane
with eyes closed!*

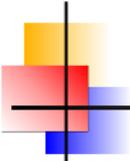
Institute Colloquium, IISER Tirupati

Gadadhar Misra

Indian Statistical Institute Bangalore and IIT Gandhinagar

April 19, 2024





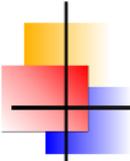
The Fundamental Theorem of Calculus

Recall the two forms of the fundamental theorem of calculus.

- The first form says that continuous $f : [a, b] \rightarrow \mathbb{R}$ admits a primitive: there exists $F : (a, b) \rightarrow \mathbb{R}$ such that $F' = f$ on (a, b) .
- The second form says: if g is continuous on $[a, b]$, differentiable on (a, b) , and g' is continuous on $[a, b]$, then

$$\int_a^b g' = g(b) - g(a).$$





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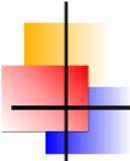
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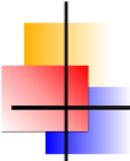
Extension to \mathbb{R}^n

What happens if the functions are defined on an open subset U of \mathbb{R}^n ?

If $f : U \rightarrow \mathbb{R}^2$ is continuous, does there exist a continuously differentiable $F : U \rightarrow \mathbb{R}$ such that

$$\frac{\partial F}{\partial x_1} = f_1, \quad \frac{\partial F}{\partial x_2} = f_2? \quad (\star)$$





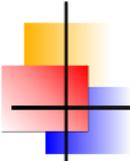
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A necessary condition

If such F exists, then we must have

$$\frac{\partial^2 F}{\partial x_2 \partial x_1} = \frac{\partial f_1}{\partial x_2}, \quad \frac{\partial^2 F}{\partial x_1 \partial x_2} = \frac{\partial f_2}{\partial x_1}. \quad (\dagger)$$

- Therefore, a necessary condition is:

$$\frac{\partial f_1}{\partial x_2} = \frac{\partial f_2}{\partial x_1}. \quad (\ddagger)$$





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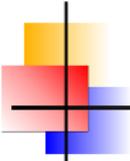
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Vector fields and potentials

The function f is called a **vector field**. If F satisfies (\dagger) , it is the **potential** (or **primitive**) of f , and f is said to be **conservative**.

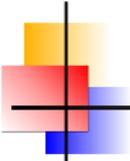
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Under certain topological conditions on U , the necessary condition becomes sufficient.





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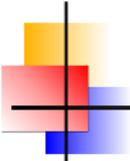
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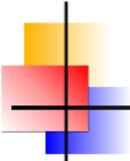
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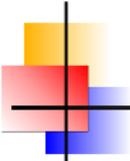
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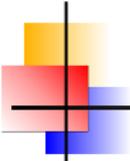


The counterexample

Let $U = \mathbb{R}^2 \setminus \{(0,0)\}$ and define $f : U \rightarrow \mathbb{R}^2$:

$$f(x_1, x_2) = \left(\frac{-x_2}{x_1^2 + x_2^2}, \frac{x_1}{x_1^2 + x_2^2} \right).$$





Checking the necessary condition

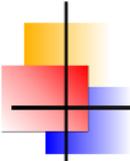
Check that (\ddagger) is satisfied:

$$\frac{\partial f_2}{\partial x_1} = \frac{x_1^2 + x_2^2 - 2x_1^2}{(x_1^2 + x_2^2)^2} = \frac{x_2^2 - x_1^2}{(x_1^2 + x_2^2)^2},$$

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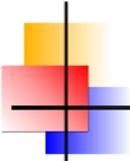
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f is not conservative

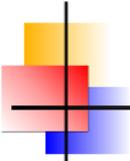
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- Then

$$\begin{aligned} \int_0^{2\pi} \frac{d}{d\theta} F(\cos \theta, \sin \theta) d\theta &= F(\cos \theta, \sin \theta) \Big|_0^{2\pi} \\ &= F(1, 0) - F(1, 0) = 0. \end{aligned}$$

We evaluate the same integral using a different method and arrive at a contradiction.





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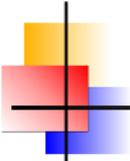
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The Chain Rule

Lemma (Chain Rule)

Suppose that $\Theta : \mathbb{R} \rightarrow \mathbb{R}^2$ and $F : \mathbb{R}^2 \rightarrow \mathbb{R}$ are differentiable functions. Then

$$D(F \circ \Theta)(t) = DF(\Theta(t))D\Theta(t), \quad t \in \mathbb{R}. \quad (b)$$





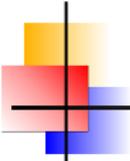
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Setting up the computation

Let $\Theta(t) = (\cos t, \sin t)$. For any $(a, b) \in \mathbb{R}^2$:

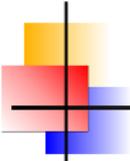
$$DF(a, b) \begin{bmatrix} u \\ v \end{bmatrix} = u \frac{\partial F}{\partial x_1}(a, b) + v \frac{\partial F}{\partial x_2}(a, b).$$

- For any $t \in \mathbb{R}$:

$$D\Theta(t)r = \begin{bmatrix} -r \sin t \\ r \cos t \end{bmatrix}, \quad r \in \mathbb{R}.$$

- Note: (i) $f_1(\cos \theta, \sin \theta) = -\sin \theta$ and (ii) $f_2(\cos \theta, \sin \theta) = \cos \theta$.





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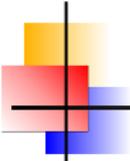
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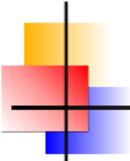
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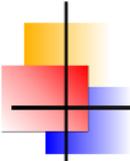




Applying the chain rule

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The contradiction

Since $D(F \circ \Theta)(t) = \frac{d}{dt}F(\cos t, \sin t)$, it follows that

$$\int_0^{2\pi} \frac{d}{dt}F(\cos t, \sin t) dt = \int_0^{2\pi} 1 dt = 2\pi.$$

But we showed that this integral equals 0. **Contradiction!**

Therefore, although f satisfies (\ddagger) , there is no F satisfying (\star) . The vector field f is not conservative.





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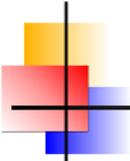
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Star-shaped domains

When is the necessary condition for the existence of a potential also sufficient?

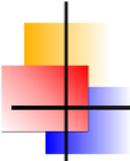
Definition

A domain $U \subset \mathbb{R}^2$ is star shaped if there is a point $x_0 \in U$ such that

$$\{x_0 + (1-t)x \mid t \in [0,1]\} \subset U$$

for all $x \in U$.





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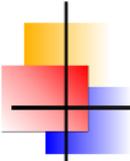
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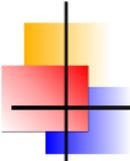
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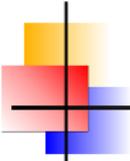


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Theorem

Let $U \subset \mathbb{R}^2$ be a star shaped open bounded set. Any continuously twice differentiable function $f : U \rightarrow \mathbb{R}^2$ satisfying (\ddagger) has a potential F .



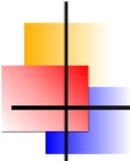


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Proof: the formula for F

WLOG, $(0,0) \in U$ and U is star shaped relative to $(0,0)$.

Define $F : U \rightarrow \mathbb{R}$ by:

$$F(x_1, x_2) = \int_0^1 (x_1 f_1(tx_1, tx_2) + x_2 f_2(tx_1, tx_2)) dt.$$

Claim: $\frac{\partial F}{\partial x_1}(x_1, x_2) = f_1(x_1, x_2)$.





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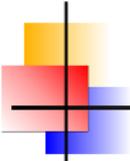
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Proof: differentiating $f(tx_1, tx_2)$ w.r.t. x_1

Think of $f(tx_1, tx_2)$ as a composition:

$$(x_1, x_2) \xrightarrow{T} (tx_1, tx_2) \xrightarrow{h} f(tx_1, tx_2).$$

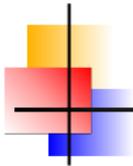
The derivative of the linear map T is $DT(x_1, x_2) = \begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix}$.

By the chain rule applied to $h \circ T$:

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Thus, applying this formula to f_1 , we have $\frac{\partial f_1}{\partial x_1}(tx_1, tx_2) = t \frac{\partial f_1}{\partial x_1}(tx_1, tx_2)$, similarly, for f_2 .





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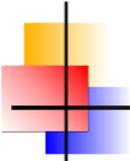
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Proof: computing $\frac{d}{dt}f_1(tx_1, tx_2)$

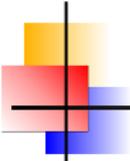
Think of $f_1(tx_1, tx_2)$ as:

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We have $D\tau(t) = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$. By the chain rule:

$$\frac{d}{dt}f_1(tx_1, tx_2) = x_1 \frac{\partial f_1}{\partial x_1}(tx_1, tx_2) + x_2 \frac{\partial f_1}{\partial x_2}(tx_1, tx_2).$$





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Proof: the product rule

Applying the product rule:

$$\begin{aligned} \frac{d}{dt}(tf_1(tx_1, tx_2)) &= f_1(tx_1, tx_2) \\ &+ tx_1 \frac{\partial f_1}{\partial x_1}(tx_1, tx_2) + tx_2 \frac{\partial f_1}{\partial x_2}(tx_1, tx_2). \end{aligned}$$





Proof: the final computation

Differentiating F under the integral sign w.r.t. x_1 :

$$\begin{aligned}\frac{\partial F}{\partial x_1} &= \int_0^1 \left\{ f_1 + tx_1 \frac{\partial f_1}{\partial x_1} + tx_2 \frac{\partial f_2}{\partial x_1} \right\} dt \\ &= \int_0^1 \left\{ \frac{d}{dt}(tf_1) + tx_2 \left(\frac{\partial f_2}{\partial x_1} - \frac{\partial f_1}{\partial x_2} \right) \right\} dt.\end{aligned}$$

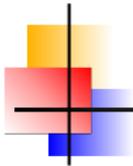
(all functions evaluated at (tx_1, tx_2))

By hypothesis, $\frac{\partial f_1}{\partial x_2} = \frac{\partial f_2}{\partial x_1}$. Therefore:

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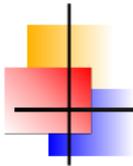
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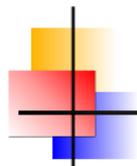
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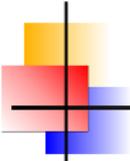


The other half of the FTC

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We must first discuss *integration* of functions on open sets and curves in \mathbb{R}^2 .





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Double integrals

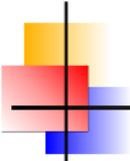
Let $U \subset [a, b] \times [c, d]$ be open and connected. Let $\Delta x_i = x_{i+1} - x_i$, $\Delta y_j = y_{j+1} - y_j$ be determined by partitions of $[a, b]$ and $[c, d]$.

For continuous f on U , the integral of f over U is:

$$\iint_U f \, dx \, dy := \lim_{\Delta x_i, \Delta y_j \rightarrow 0} \sum_{i=1}^m \sum_{j=1}^n f(x_i, y_j) \Delta x_i \Delta y_j,$$

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Let $F : U \rightarrow \mathbb{R}^2$ be continuously differentiable and $\gamma : [0, 1] \rightarrow \mathbb{R}^2$ continuously differentiable with $\gamma'(t) > 0$ and $\partial U = \text{ran } \gamma$.

The path integral of F over γ is:

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A region U is called **simple** if ∂U is parametrized by a continuously differentiable $\gamma : [a, b] \rightarrow U$ tracing ∂U once counterclockwise.





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Detecting holes: grad and curl

The final task: find invariants for U to detect if it has a hole.

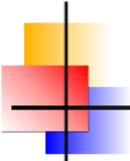
Let $C^\infty(U, \mathbb{R}^k)$ be the space of smooth functions. Define:

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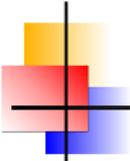
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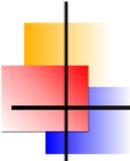
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$$\{0\} \rightarrow C^\infty(U, \mathbb{R}) \xrightarrow{\text{grad}} C^\infty(U, \mathbb{R}^2) \xrightarrow{\text{curl}} C^\infty(U, \mathbb{R}) \rightarrow \{0\}$$

is a **complex**. The quotient

$$H^1(U) := \ker(\text{curl}) / \text{Im}(\text{grad})$$

is, quite surprisingly, **finite dimensional**.

- If U is star shaped, then $H^1(U) = \{0\}$.
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Thank You!

